

Gravitational Instability

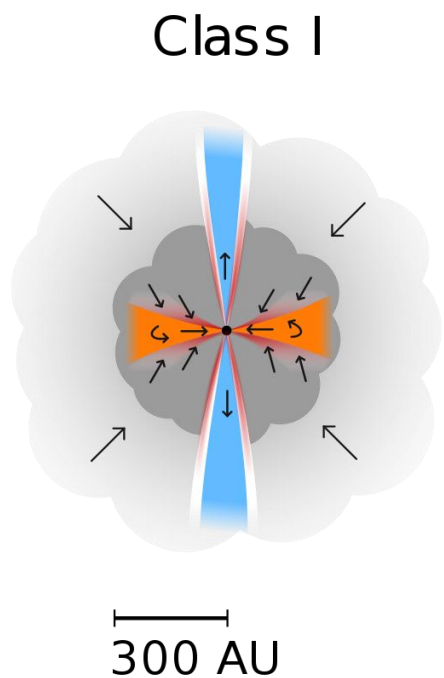
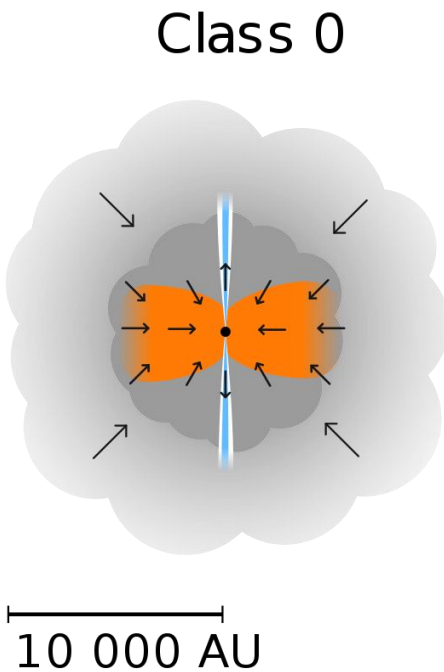
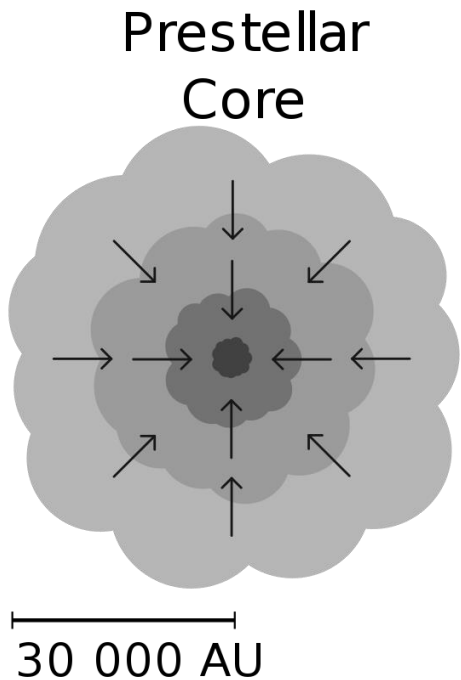
Richard Booth

Royal Society University Research Fellow
Imperial College London

THE
ROYAL
SOCIETY

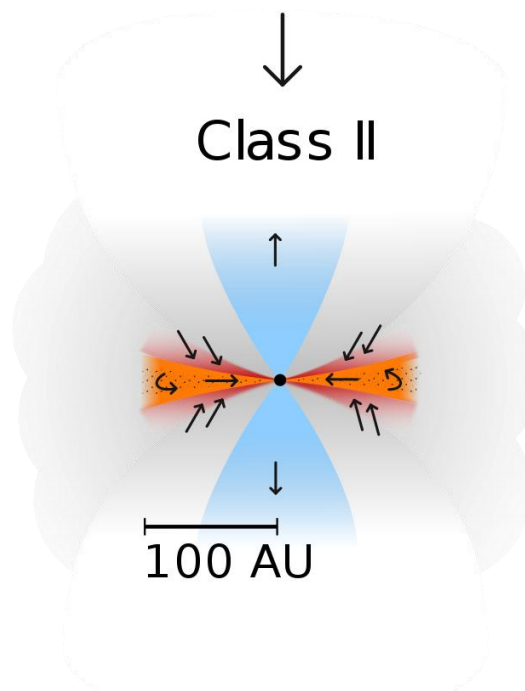
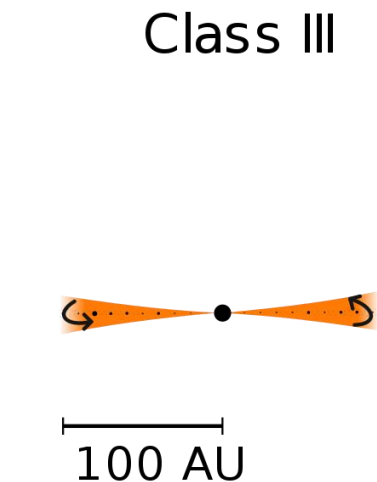
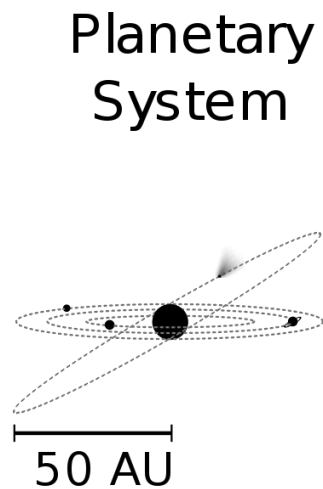


All mass in cloud



Comparable mass in star/cloud/disc

All mass in star



When are discs gravitationally unstable?

- Toomre's Q parameter
- Ratio of stabilizing to destabilizing forces
 - $Q < 1$: Instability

Pressure

Rotation

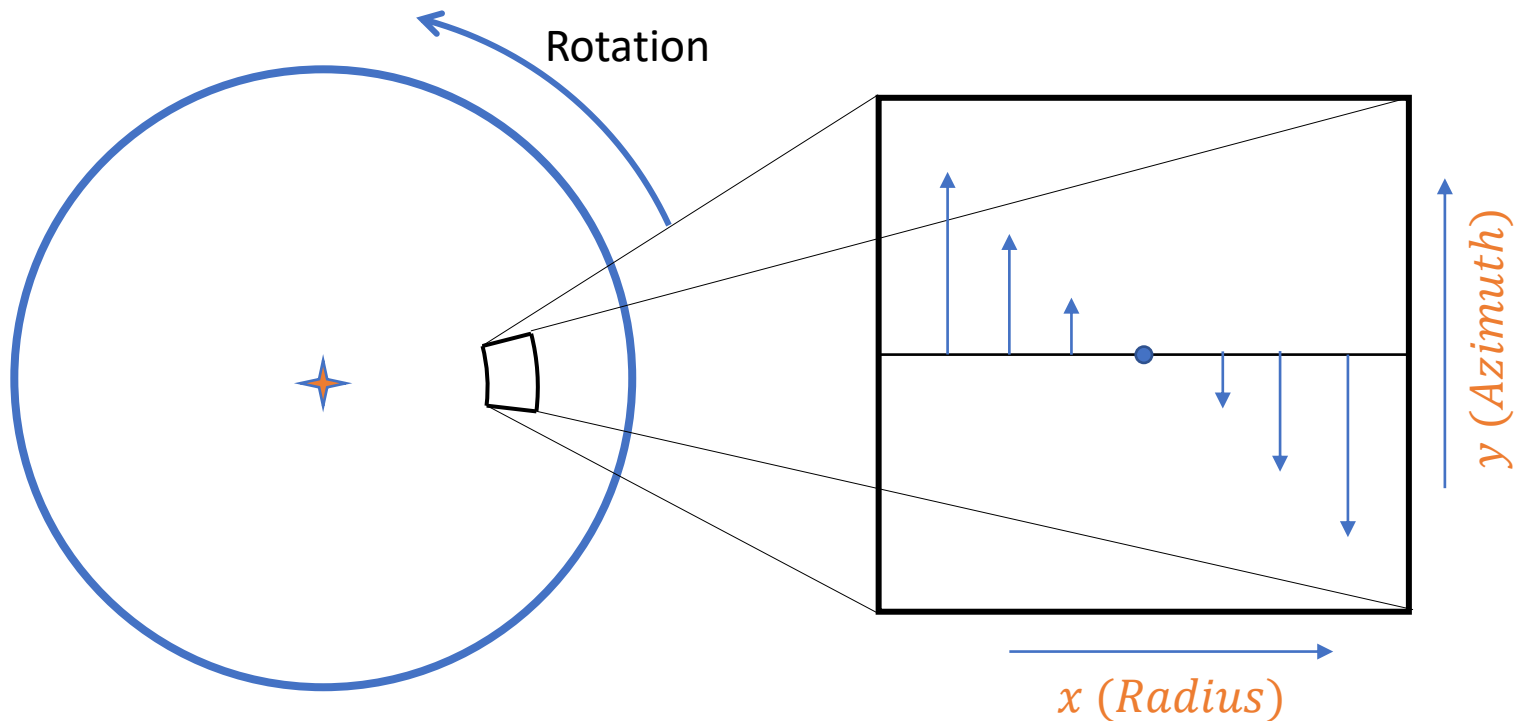
$$Q = \frac{c_s \Omega}{\pi G \Sigma}$$

Gravity

The diagram illustrates the Toomre Q parameter equation, $Q = \frac{c_s \Omega}{\pi G \Sigma}$. Three orange arrows point from the labels 'Pressure', 'Rotation', and 'Gravity' to the terms in the equation. 'Pressure' points to c_s , 'Rotation' points to Ω , and 'Gravity' points to $\pi G \Sigma$.

Origin of the Toomre Q

Shearing-box Geometry

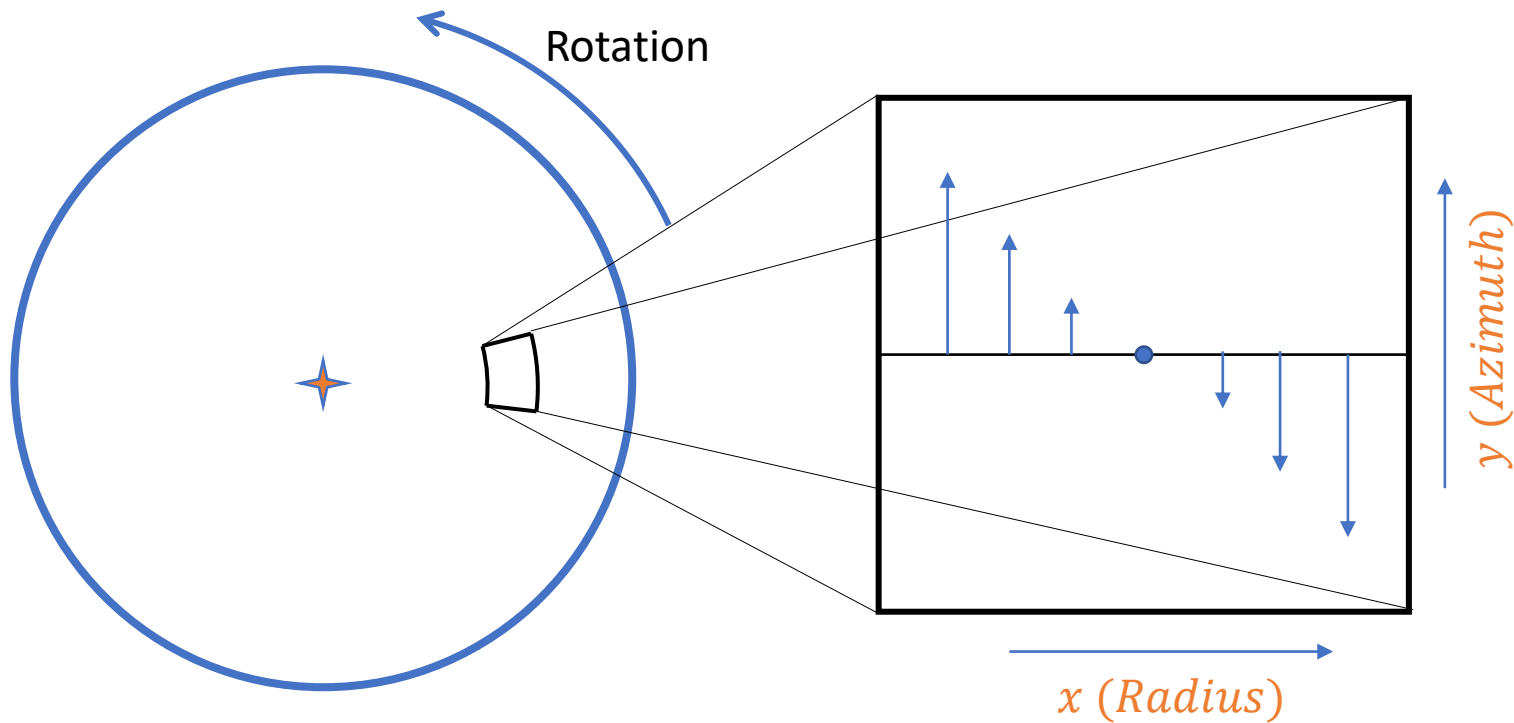


Shearing Box Model:

- Small patch of disc
- Rotates with the fluid
- $\frac{d\Omega}{dr}$ introduces *shear*
- Also: *thin disc approximation*

Origin of the Toomre Q

Shearing-box Geometry

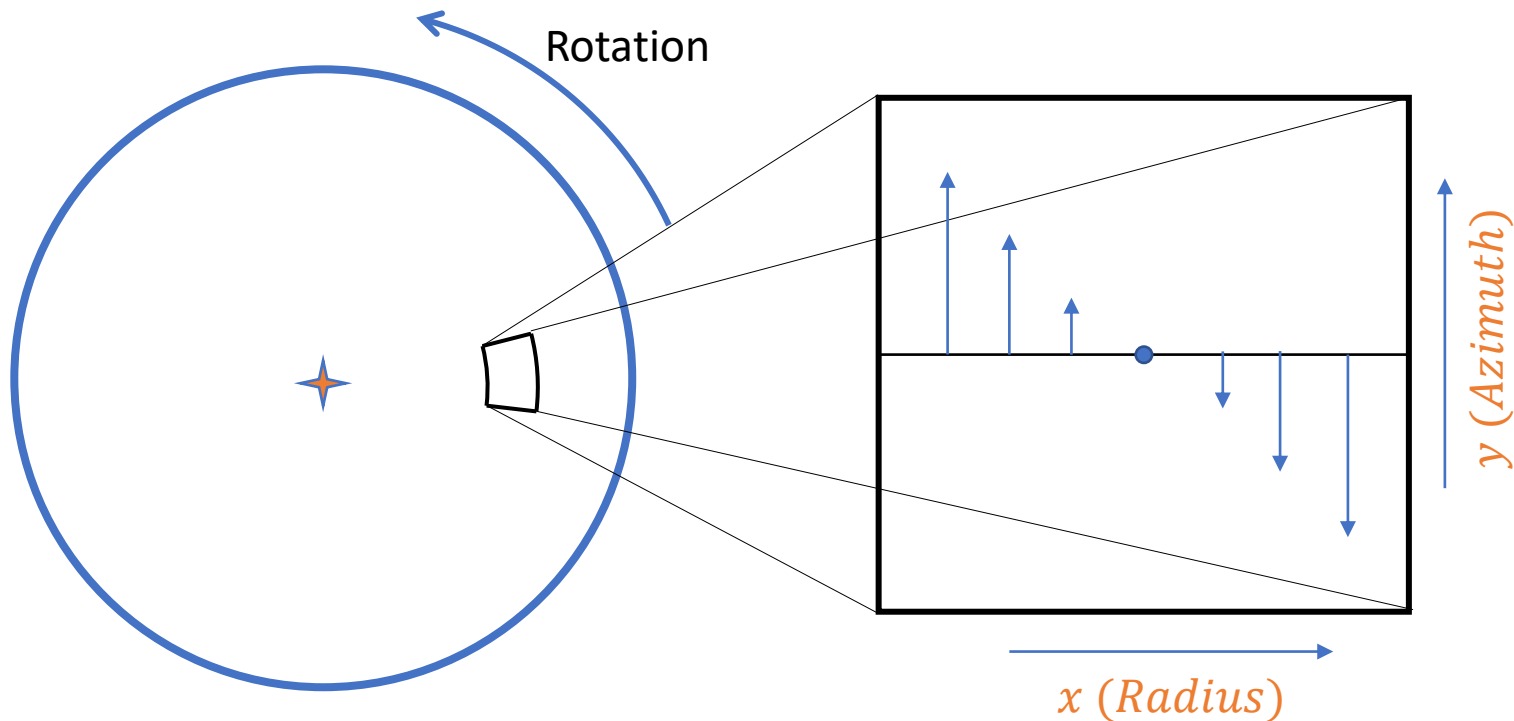


Fluid equations

$$\frac{d\Sigma}{dt} + \nabla \cdot (\Sigma \vec{v}) = 0 \quad (\text{Continuity})$$

Origin of the Toomre Q

Shearing-box Geometry



Fluid equations

$$\frac{d\Sigma}{dt} + \nabla \cdot (\Sigma \vec{v}) = 0 \quad (\text{Continuity})$$

$$\frac{d\vec{v}}{dt} + (\vec{v} \cdot \nabla) \vec{v} = -\frac{\nabla P}{\Sigma} - \nabla\Phi - 2\vec{\Omega} \times \vec{v} + 3\Omega x \vec{e}_x$$

Pressure

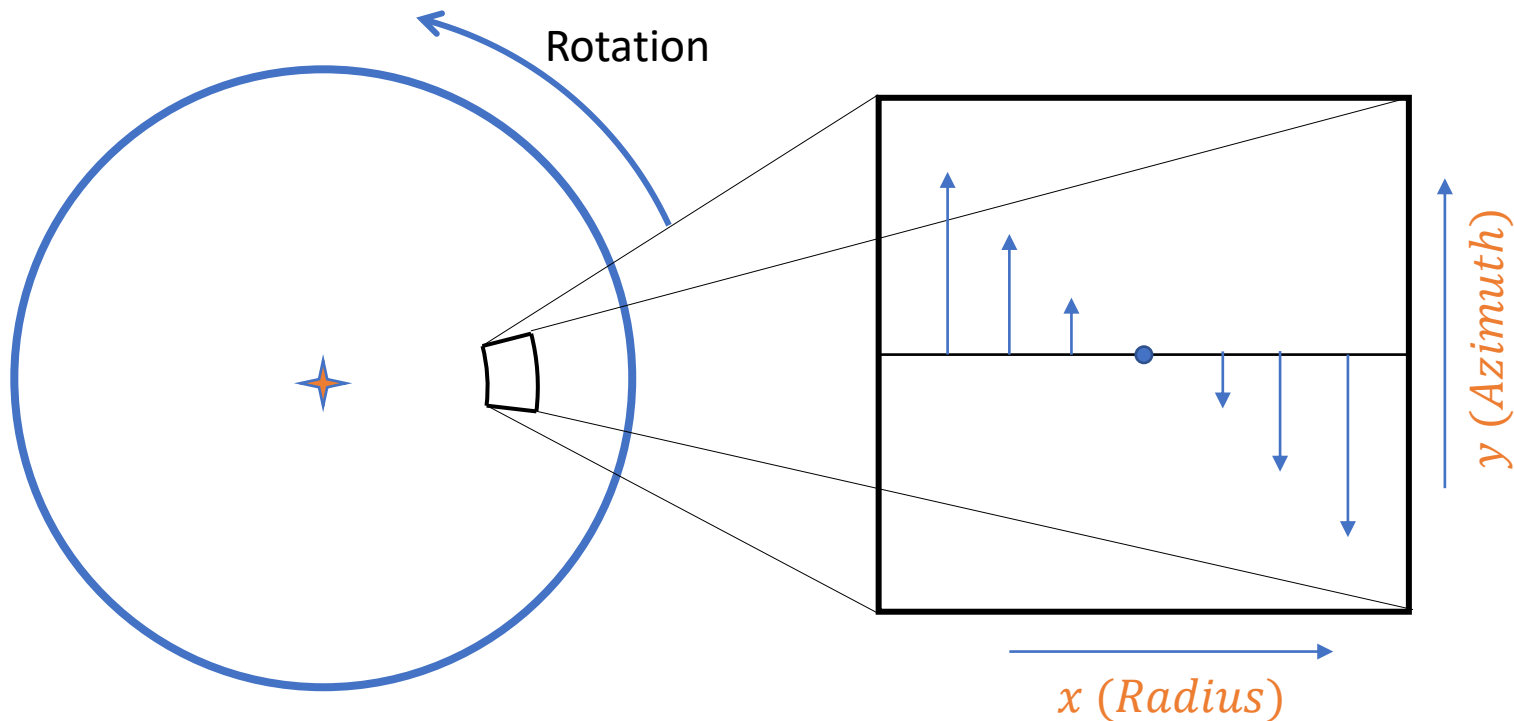
Self-gravity

Coriolis

Shear

Origin of the Toomre Q

Shearing-box Geometry



Fluid equations

$$\frac{d\Sigma}{dt} + \nabla \cdot (\Sigma \vec{v}) = 0 \quad (\text{Continuity})$$

$$\frac{d\vec{v}}{dt} + (\vec{v} \cdot \nabla) \vec{v} = -\frac{\nabla P}{\Sigma} - \nabla \Phi - 2\vec{\Omega} \times \vec{v} + 3\Omega x \vec{e}_x$$

(Momentum)

$$P = \Sigma c_s^2 \quad \nabla^2 \Phi = 4\pi G \Sigma \cdot \delta(z)$$

(Pressure) (Gravity)

Origin of the Toomre Q

Equilibrium solution

Fluid equation	Background solution
$\frac{d\Sigma}{dt} + \nabla \cdot (\Sigma \vec{v}) = 0$ (Continuity)	$\Sigma = \Sigma_0 = \text{const.}$
$P = \Sigma c_s^2$ (Pressure)	$c_s = \text{const.}$

Origin of the Toomre Q

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Origin of the Toomre Q

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Neglect left hand side [i.e. $(\vec{v} \cdot \nabla) \vec{v} = 0$]:

$$0 = -2\Omega v_y + 3\Omega x \quad (\text{x equation})$$

$$0 = +2\Omega v_x \quad (\text{y equation})$$

Origin of the Toomre Q

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$$0 = +2\Omega v_x \quad (\text{y equation})$$

Solution:

$$v_x = 0, \quad v_y = \frac{3}{2}\Omega x$$

(obeys $(\vec{v} \cdot \nabla) \vec{v} = 0$!)

Origin of the Toomre Q

Equilibrium solution

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Origin of the Toomre Q

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$\frac{d\vec{v}}{dt} + (\vec{v} \cdot \nabla) \vec{v} = -\frac{\nabla P}{\Sigma} - 2\vec{\Omega} \times \vec{v} + 3\Omega x \vec{e}_x - \nabla \Phi$ (Momentum)	$v_x = 0, \quad v_y = \frac{3}{2}\Omega x$ (const. shear)

Perturb Σ , \vec{v} and Φ :

$$\begin{aligned} \Sigma &= \Sigma_0 + \tilde{\Sigma} \\ v_x &= \tilde{v}_x \\ v_y &= \frac{3}{2}\Omega x + \tilde{v}_y \\ \Phi &= \tilde{\Phi} \end{aligned}$$

Look axisymmetric solutions of the form

$$\tilde{f} = |f| \exp(st + ikx)$$

Origin of the Toomre Q

Perturb equilibrium

Fluid equation	Perturbation equation
$\frac{d\Sigma}{dt} + \nabla \cdot (\Sigma \vec{v}) = 0 \quad (\text{Continuity})$	$s\tilde{\Sigma} = -ik\Sigma_0\tilde{v}_x$
$\nabla^2\Phi = 4\pi G\Sigma \cdot \delta(z) \quad (\text{Gravity})$	$\tilde{\Phi} = -\frac{2\pi G\tilde{\Sigma}}{k}$
$\frac{dv_x}{dt} + (\vec{v} \cdot \nabla)v_x = -\frac{c_s^2}{\Sigma} \frac{dP}{dx} + 2\Omega v_y + 3\Omega x - \frac{d\Phi}{dx}$	$s\tilde{v}_x = -\frac{c_s^2}{\Sigma_0} ik\tilde{\Sigma} + 2\Omega \tilde{v}_y - ik\tilde{\Phi}$
$\frac{dv_y}{dt} + (v \cdot \nabla)v_y = 2\Omega v_x$	$s\tilde{v}_y = \frac{1}{2}\Omega \tilde{v}_x$

Look for solutions of the form
$$\tilde{f} = |f|\exp(st + ikx)$$

Origin of the Toomre Q

Perturb equilibrium

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$\frac{dv_x}{dt} + (\vec{v} \cdot \nabla)v_x = -\frac{c_s^2}{\Sigma} \frac{dP}{dx} - \frac{d\Phi}{dx} + 2\Omega v_y + 3\Omega x$	$s\tilde{v}_x = -\frac{c_s^2}{\Sigma_0} ik\tilde{\Sigma} + 2\Omega \tilde{v}_y - ik\tilde{\Phi}$
$\frac{dv_y}{dt} + (v \cdot \nabla)v_y = 2\Omega v_x$	$s\tilde{v}_y = \frac{1}{2}\Omega \tilde{v}_x$

Next:

- Replace, $\tilde{\Sigma}$, $\tilde{\Phi}$, and \tilde{v}_y with expressions for \tilde{v}_x

Look for solutions of the form

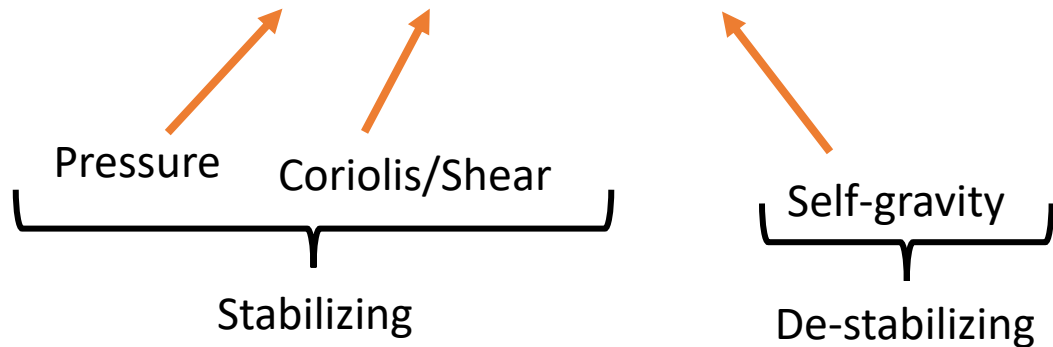
$$\tilde{f} = |f|\exp(st + ikx)$$

Origin of the Toomre Q

Perturbed equation for \tilde{v}_x

$$s\tilde{v}_x = -\frac{c_s^2}{\Sigma_0} ik\tilde{\Sigma} + 2\Omega \tilde{v}_y - ik\tilde{\Phi}$$

$$s^2\tilde{v}_x = -c_s^2 k^2\tilde{v}_x - \Omega^2 \tilde{v}_x + 2\pi G\Sigma_0\Omega k\tilde{v}_x$$



Perturbation equation

$$s\tilde{\Sigma} = -ik\Sigma_0\tilde{v}_x$$

$$\tilde{\Phi} = -\frac{2\pi G\tilde{\Sigma}}{k}$$

$$s\tilde{v}_x = -\frac{c_s^2}{\Sigma_0} ik\tilde{\Sigma} + 2\Omega \tilde{v}_y - ik\tilde{\Phi}$$

$$s\tilde{v}_y = \frac{1}{2}\Omega \tilde{v}_x$$

Origin of the Toomre Q

Perturbed equation for \tilde{v}_x

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$$s^2\tilde{v}_x = -c_s^2 \mathbf{k}^2 \tilde{v}_x - \Omega^2 \tilde{v}_x + 2\pi G \Sigma_0 \Omega \mathbf{k} \tilde{v}_x$$

Instability exists when $s^2 > 0$.

From the quadratic equation:

$$ax^2 + bx + c > 0$$

we know solutions exist for $b^2 > 4ac$.

Perturbation equation

$$s\tilde{\Sigma} = -ik\Sigma_0\tilde{v}_x$$

$$\tilde{\Phi} = -\frac{2\pi G\tilde{\Sigma}}{k}$$

$$s\tilde{v}_x = -\frac{c_s^2}{\Sigma_0} ik\tilde{\Sigma} + 2\Omega \tilde{v}_y - ik\tilde{\Phi}$$

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Origin of the Toomre Q

Perturbed equation for \tilde{v}_x

$$s\tilde{v}_x = -\frac{c_s^2}{\Sigma_0} ik\tilde{\Sigma} + 2\Omega \tilde{v}_y - ik\tilde{\Phi}$$

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Instability exists when $s^2 > 0$.

From the quadratic equation:

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Hence:

$$4(\pi G\Sigma_0)^2 > 4c_s^2\Omega^2 \quad \text{or} \quad \frac{1}{Q^2} > 1$$

Perturbation equation

$$s\tilde{\Sigma} = -ik\Sigma_0\tilde{v}_x$$

$$\tilde{\Phi} = -\frac{2\pi G\tilde{\Sigma}}{k}$$

$$s\tilde{v}_x = -\frac{c_s^2}{\Sigma_0} ik\tilde{\Sigma} + 2\Omega \tilde{v}_y - ik\tilde{\Phi}$$

$$s\tilde{v}_y = \frac{1}{2}\Omega \tilde{v}_x$$

Q^2 is the ratio of the two stabilizing forces to the square of the destabilizing forces.

Origin of the Toomre Q

Fastest growing modes

$$s^2 = -c_s^2 k^2 - \Omega^2 \tilde{v}_x + 2\pi G \Sigma_0 \Omega k$$

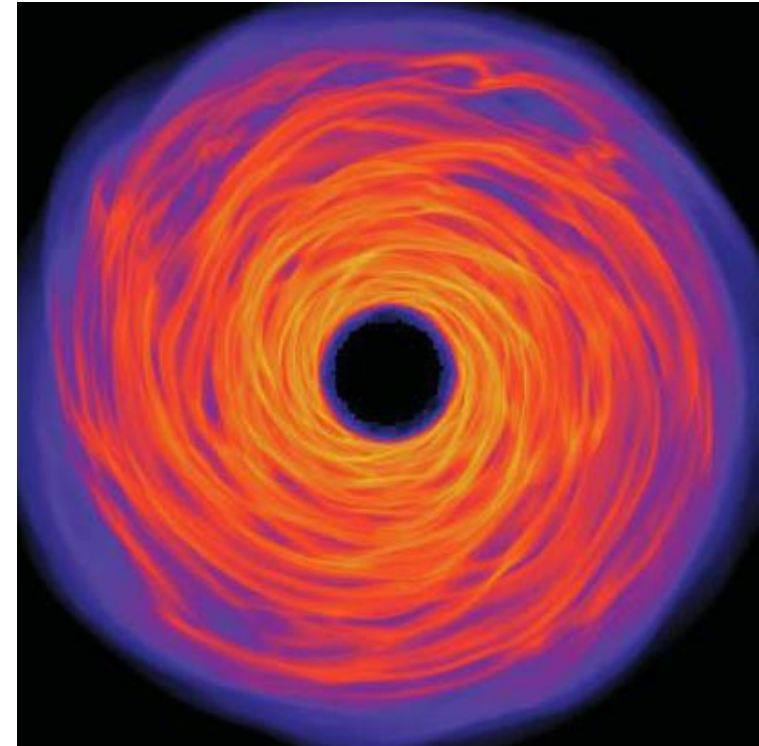
Write $H = c_s/\Omega$ and rescale:

$$\left(\frac{s}{\Omega}\right)^2 = -(kH)^2 - 1 + \frac{2}{Q} (kH)$$

Fastest growing mode has $\frac{ds}{d(kH)} = 0$.

$$\rightarrow (kH)_{\max} = 1/Q$$

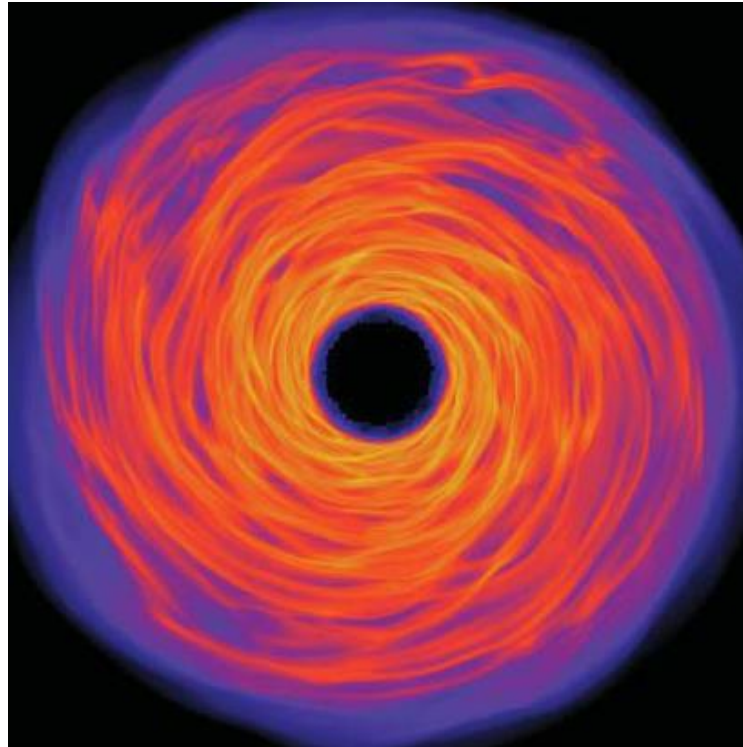
$$\left(\frac{s}{\Omega}\right)_{\max}^2 = \frac{1}{Q^2} - 1$$



Outcome of Gravitational Instability

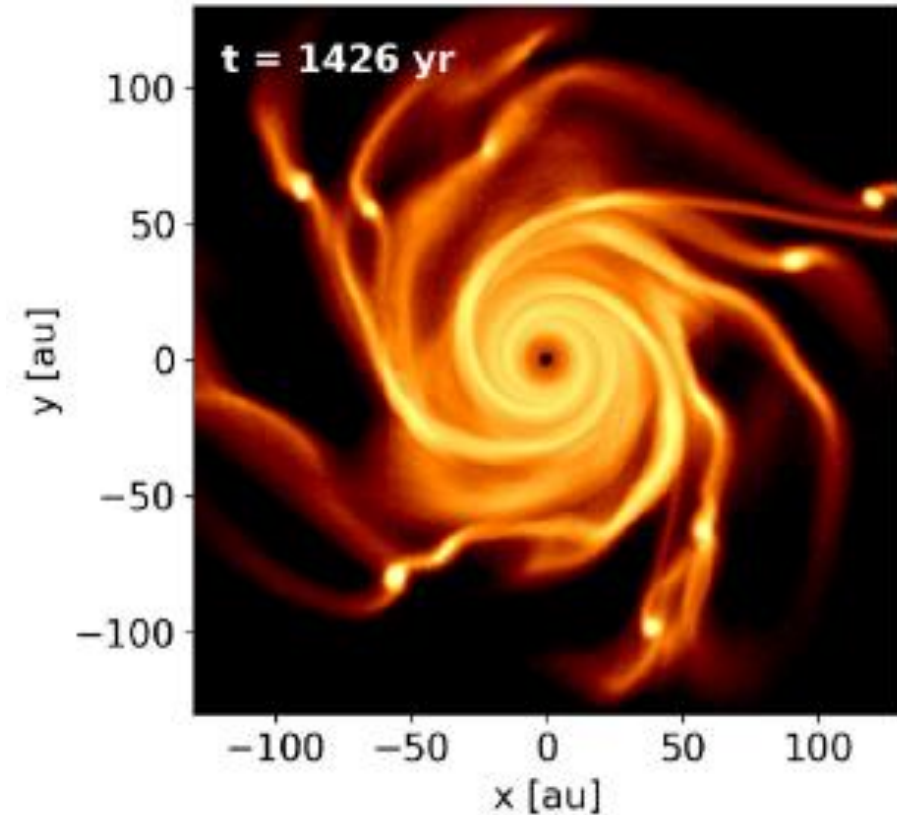
Outcome of Gravitational Instability

Quasi-steady accretion



Simulation from Booth & Clarke (2016)

Fragmentation



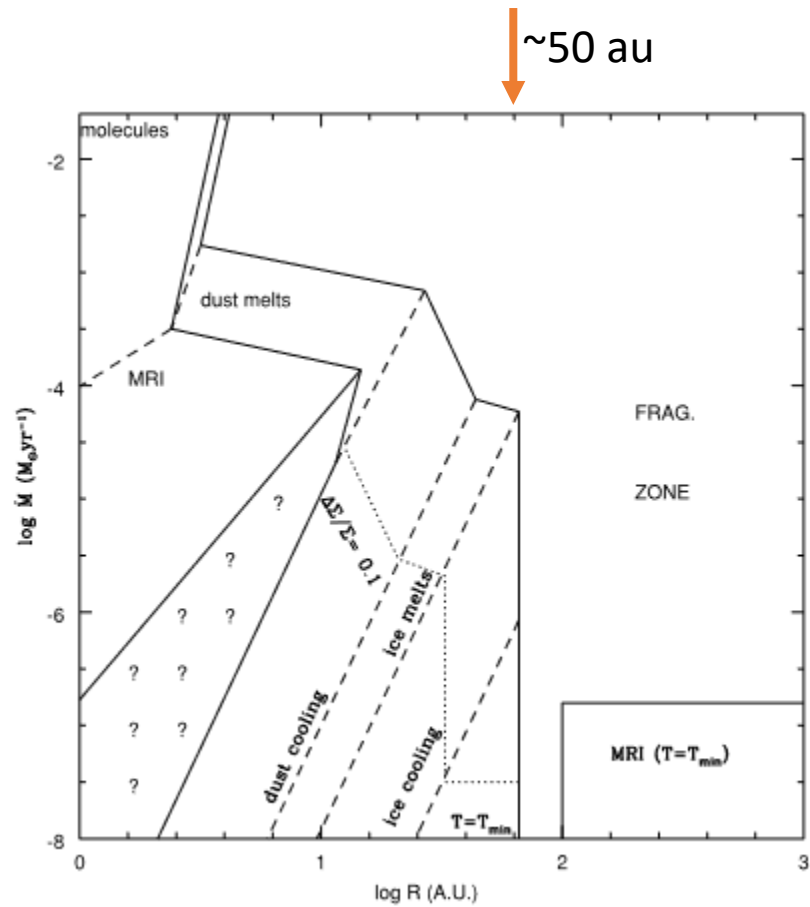
Simulation from Ilee et al. (2017)

Cooling dictates the outcome:
Fast cooling ($\tau_{cool} < 3\Omega^{-1}$):
→ fragmentation

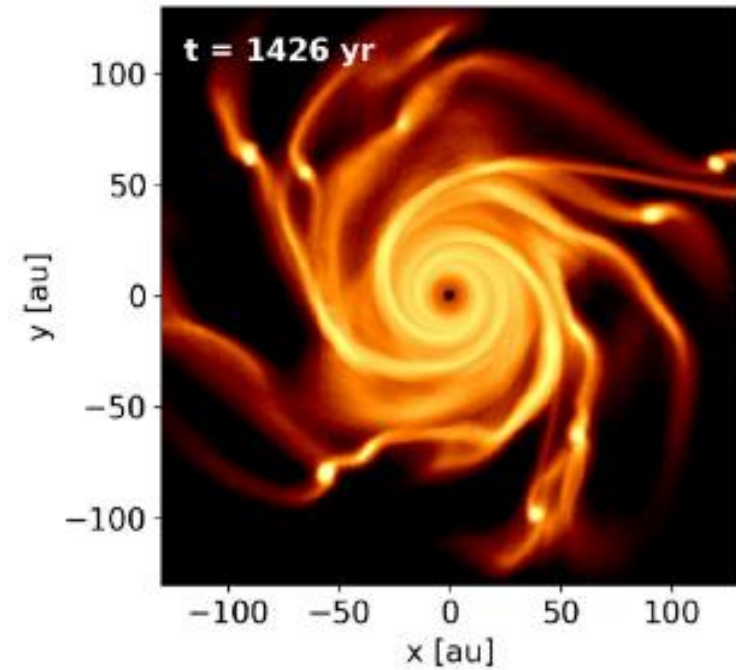
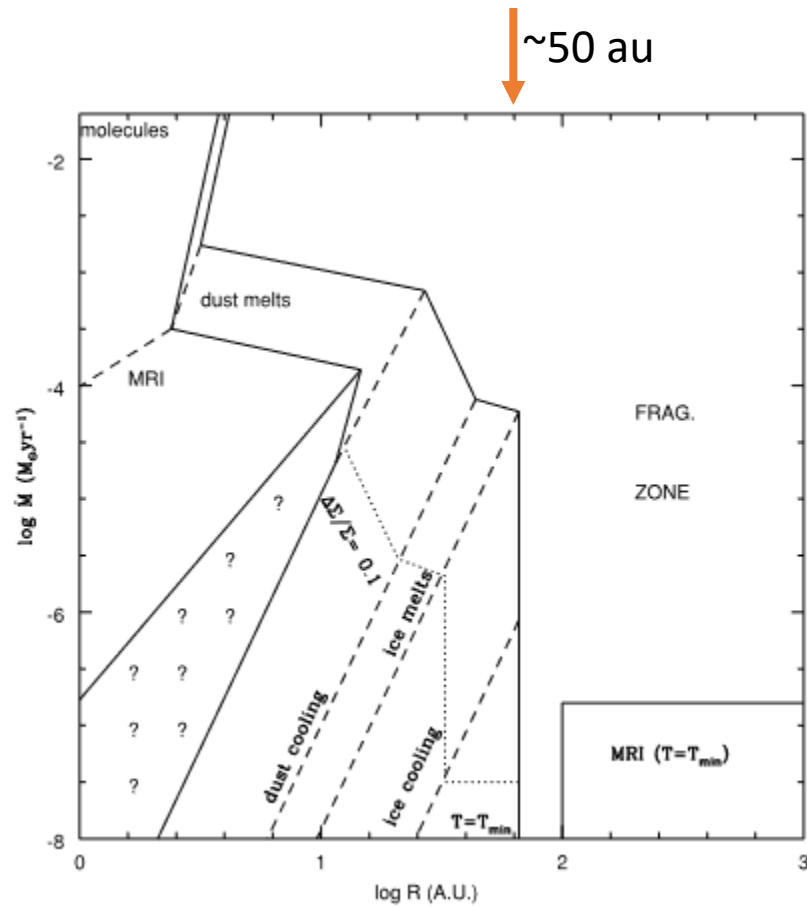
Outcome of Gravitational Instability

Fragmentation

Where do discs fragment?



Where do discs fragment?



Simulation from Ilee et al. (2017)

Does fragmentation produce planets?

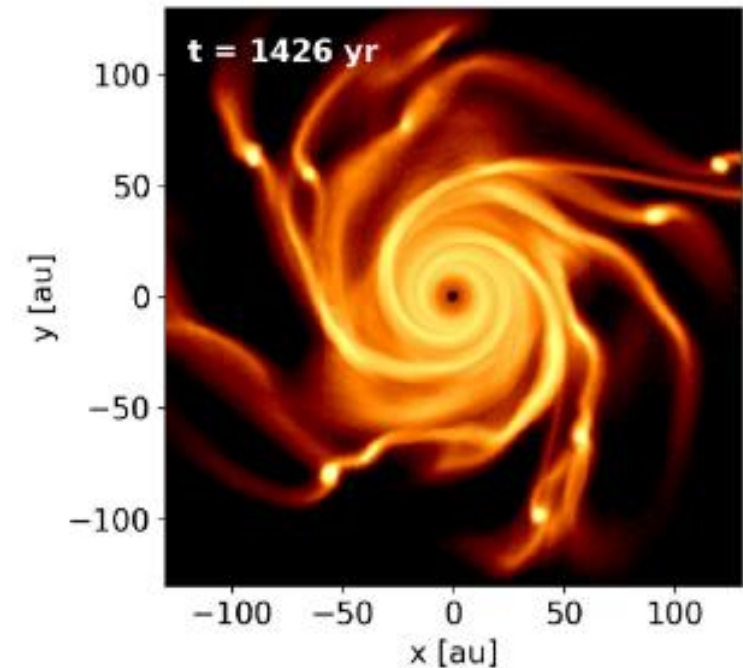
- Initial fragment masses:
 - Set by size of the collapsing region
 - \sim Wavelength of most unstable mode

$$M_{frag} \sim \Sigma \lambda^2$$

Since $kH = \frac{1}{Q}$ and $Q = \frac{c_s \Omega}{\pi G \Sigma} = \frac{H \Omega^2}{\pi G \Sigma}$:

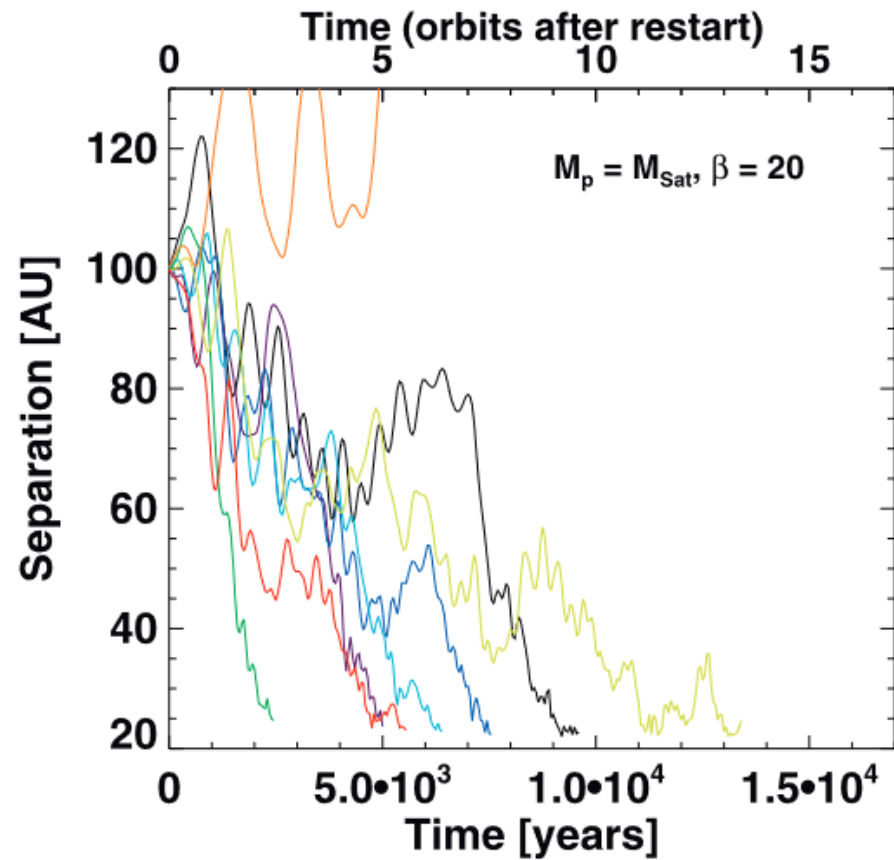
$$M_{frag} \sim 4\pi Q \left(\frac{H}{R}\right)^3 M_*$$
$$\approx 10M_J$$

Fragments are super-Jupiter or Brown Dwarf mass objects



Fate of the fragments

Fast migration

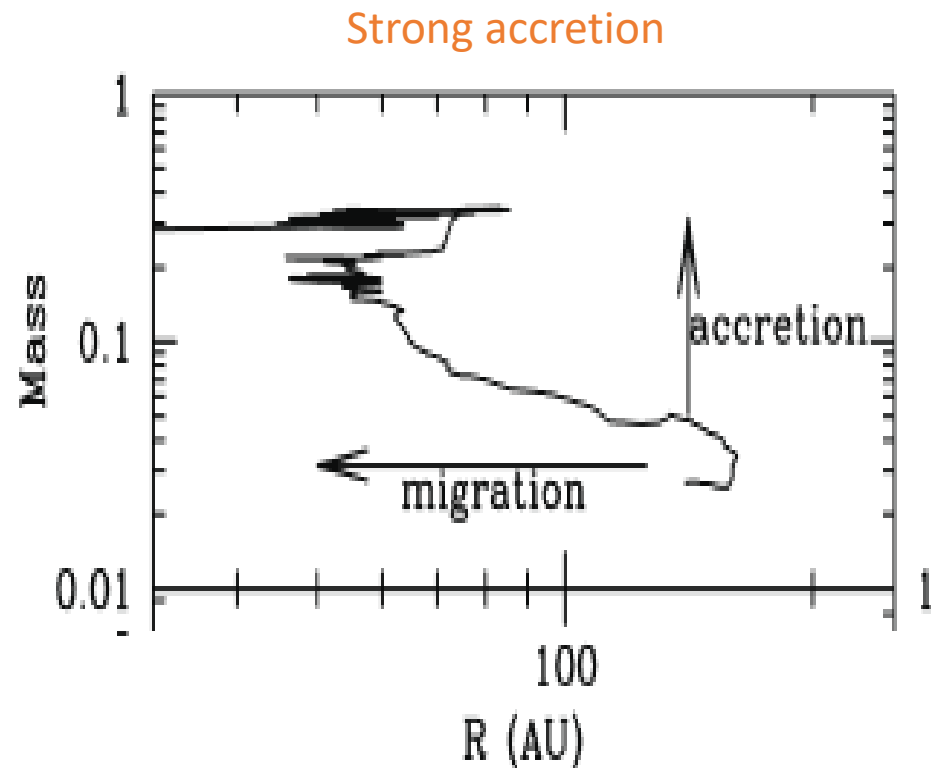


- Saturn-mass planet
- Similar results for all planet masses

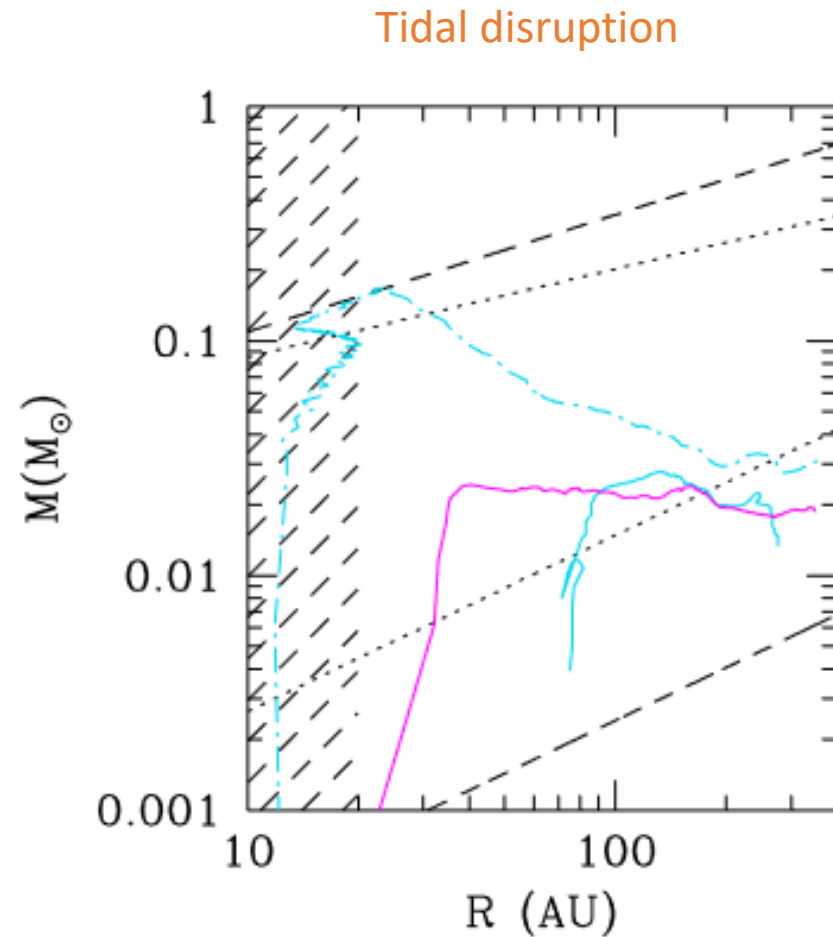
Baruteau+ (2011)

Fate of the fragments

Disruption, or high masses



Giant planets are likely a rare outcome of GI

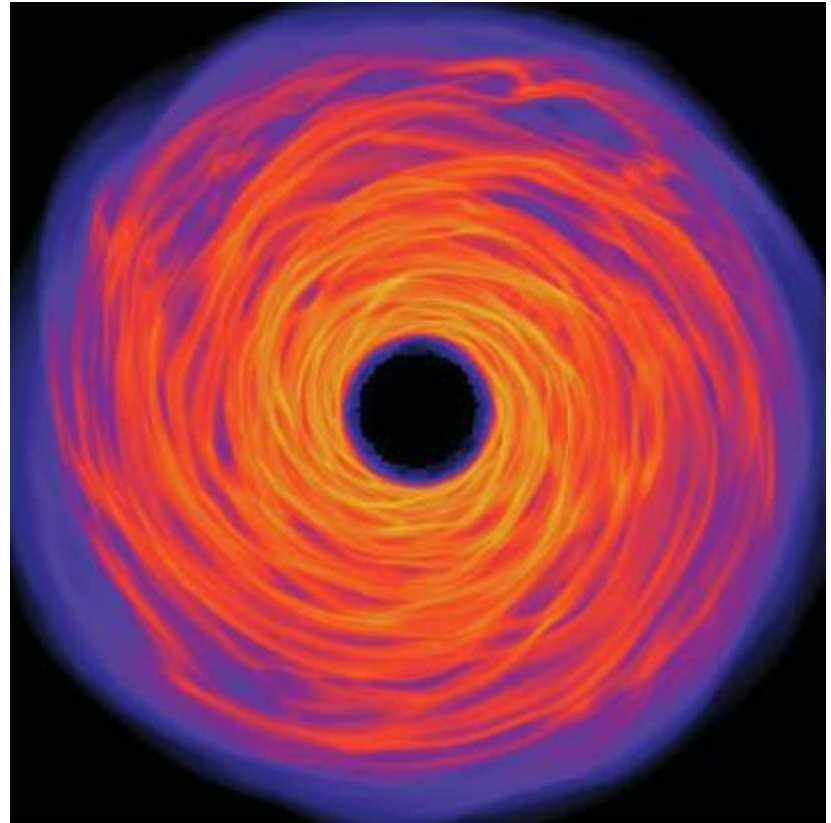


Zhu+ (2012)

Outcome of Gravitational Instability

Quasi-steady gravito-turbulence

Why is there a quasi-steady state?



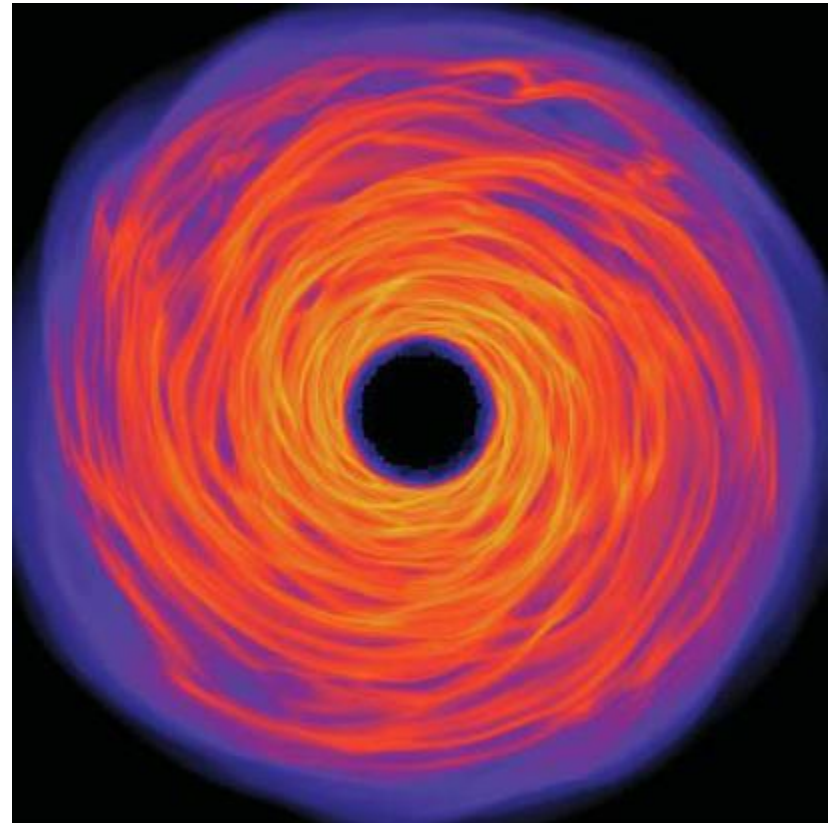
Why is there a quasi-steady state?

Let's look at the growth rate of GI:

$$\left(\frac{s}{\Omega}\right)^2 = -(kH)^2 - 1 + \frac{2}{Q} (kH)$$

With the fastest growing mode:

$$\left(\frac{s}{\Omega}\right)_{\max}^2 = \frac{1}{Q^2} - 1$$



Why is there a quasi-steady state?

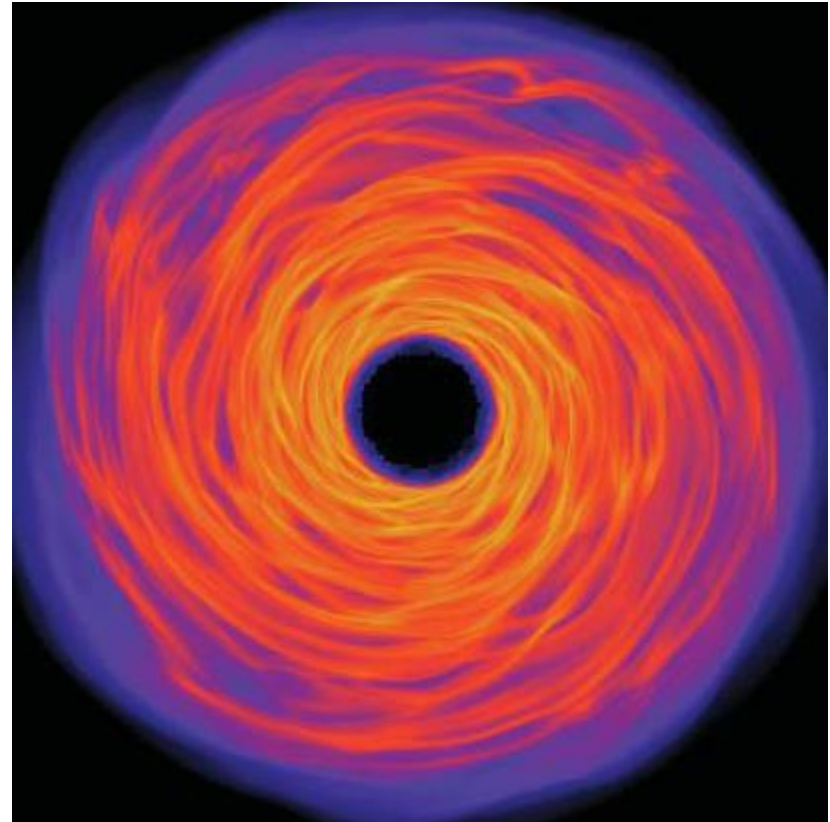
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Cooling brings Q *just* low enough that GI grows *just* fast enough to replenish the lost energy



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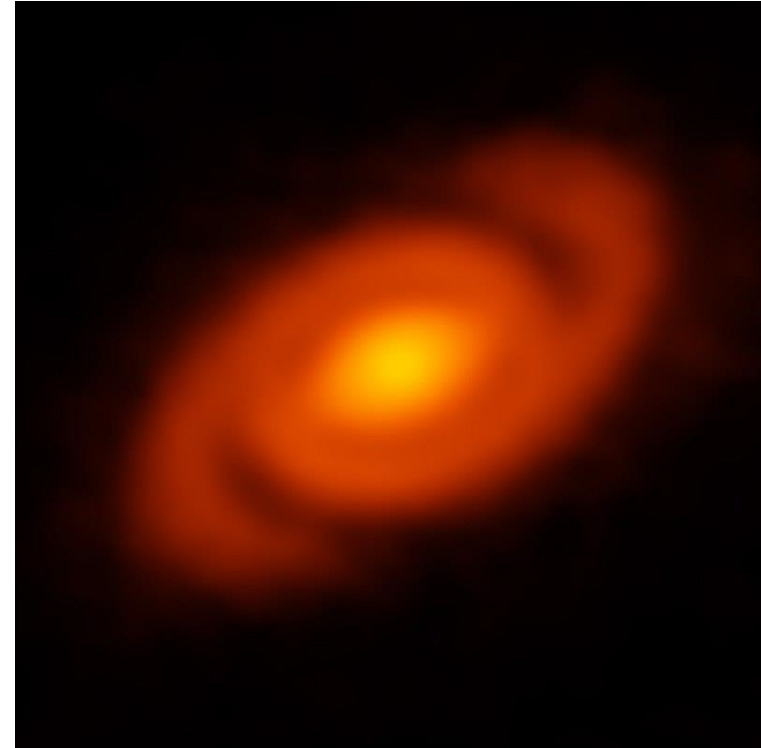
With the fastest growing mode:

$$\left(\frac{s}{\Omega}\right)_{\max}^2 = \frac{1}{Q^2} - 1$$

Cooling brings Q just low enough that GI grows just fast enough to replenish the lost energy

Isothermal simulations can't self-regulate

→ *they are much more prone to fragmentation*



Is Elias 27 a post-fragmentation system? (Perez et al. 2016)

Local nature of gravito-turbulence

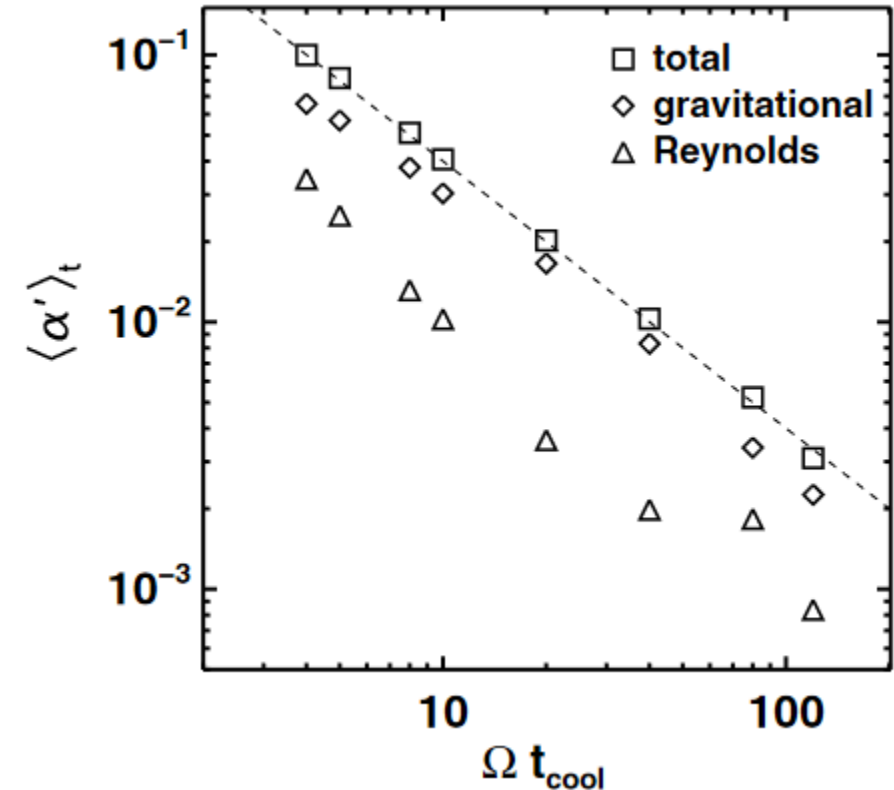
Effective viscosity

- Q and s depend on the cooling rate
→ Physical properties depend on cooling

Most famous is the effective viscosity:

$$\alpha = \frac{4}{9\gamma(\gamma-1)} \frac{1}{\tau_{cool}\Omega} \quad (\text{Gammie 2001})$$

- Requires heating/cooling to occur in the same place



(Shi & Chiang 2015)

Local nature of gravito-turbulence

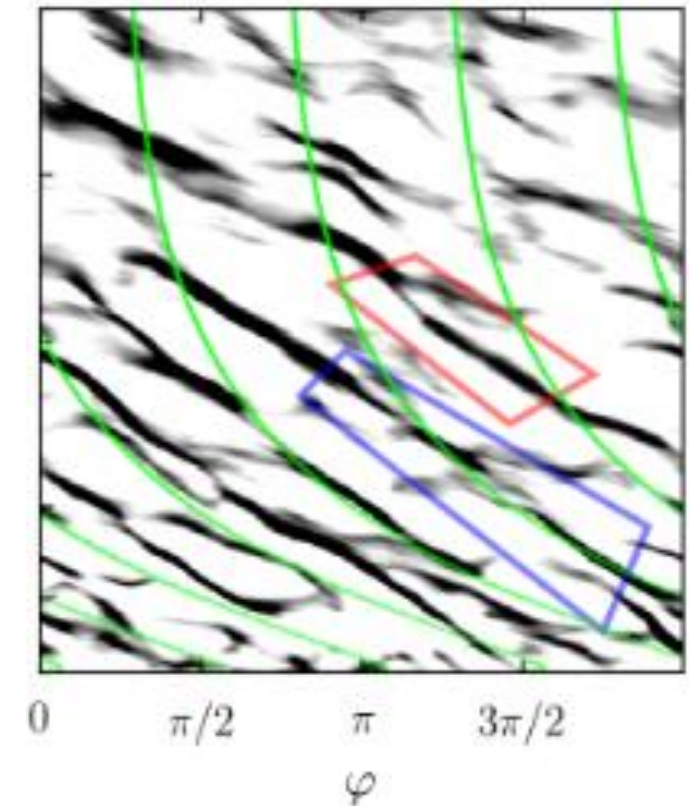
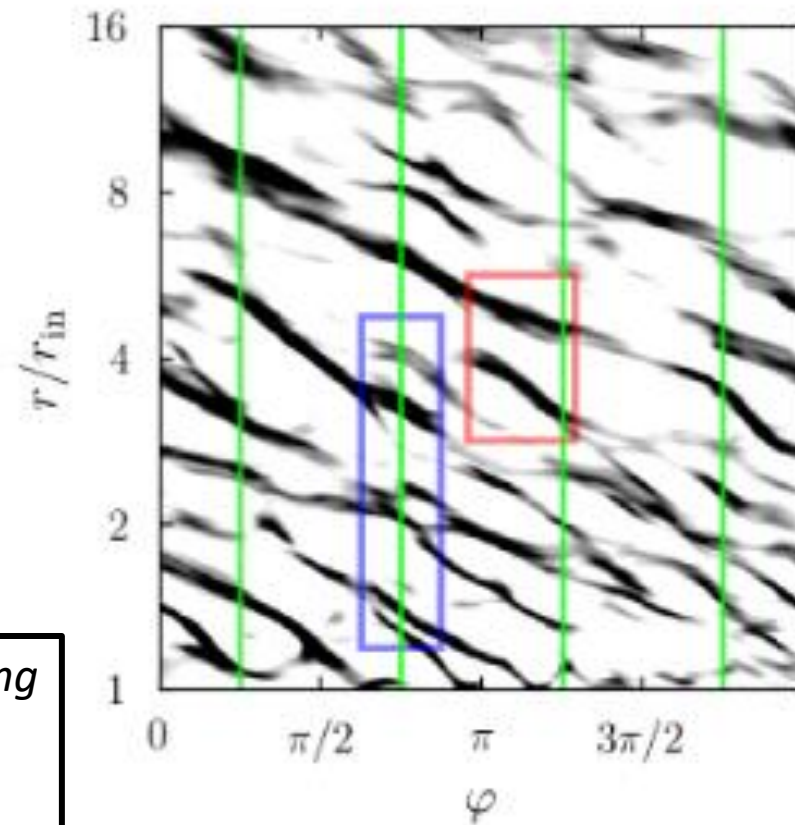
Spiral structure at two times

Green:

- Show Keplerian motion

Red/Blue:

- Demonstrate formation + destruction of large features



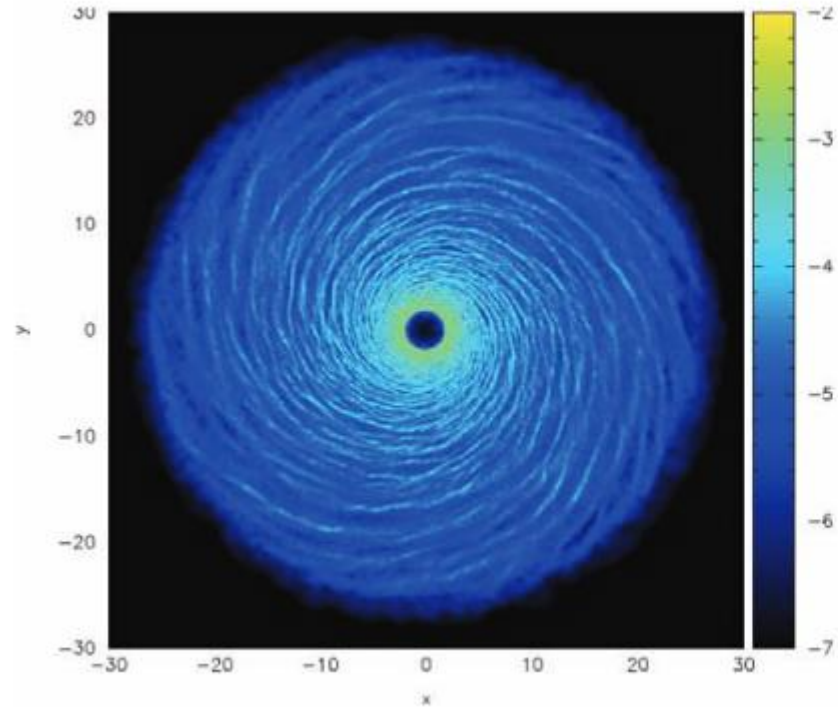
Gravito-turbulence is not travelling waves, but features that appear and disappear on orbital time-scales

Structure depends on disc mass

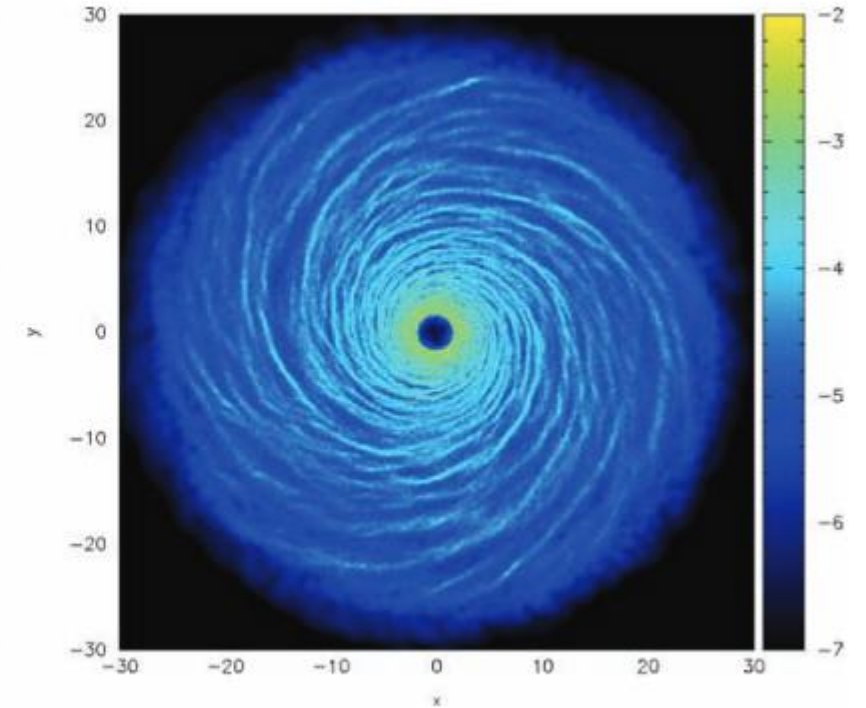
Number of spiral arms depends on disc mass.

Why?

Less Massive



More Massive



Cossins+ (2009)

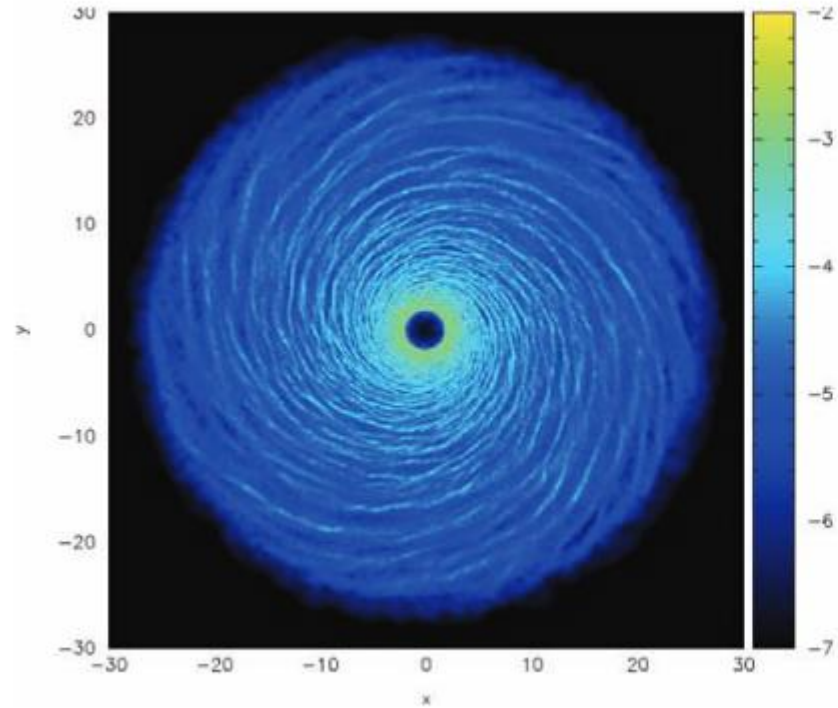
Dependence on disc mass

Number of spiral arms depends on disc mass.

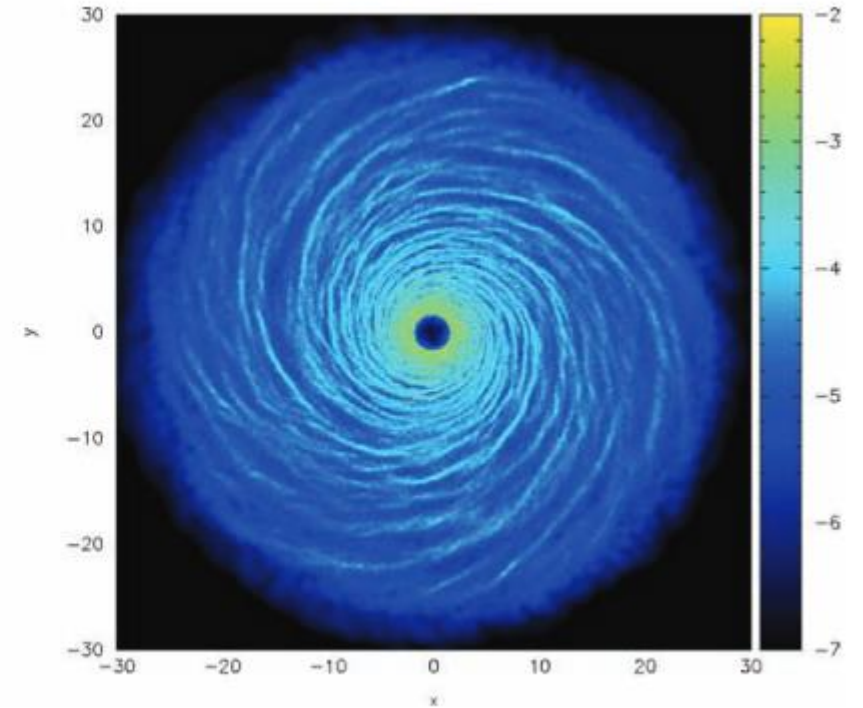
Why?

$$c_s = Q \frac{\pi G \Sigma}{\Omega}$$

Less Massive



More Massive



Dependence on disc mass

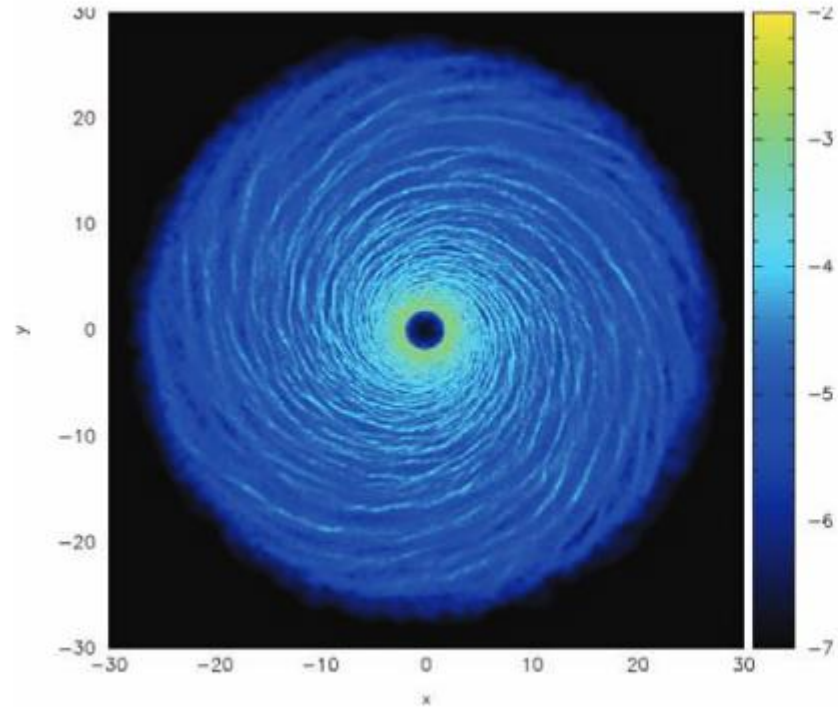
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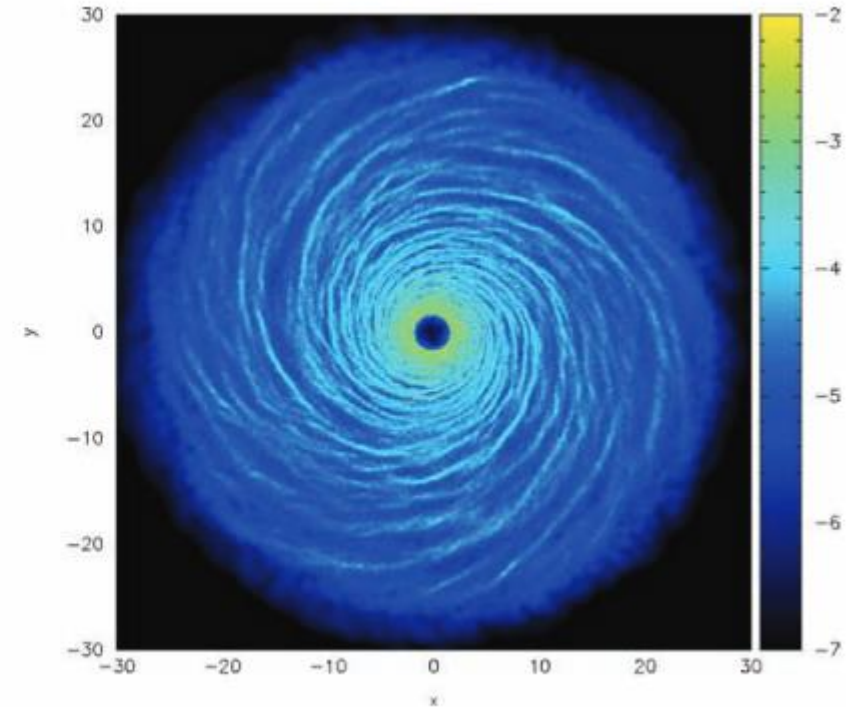
$$c_s = Q \frac{\pi G \Sigma}{\Omega}$$

$$H = Q \frac{\pi G \Sigma}{\Omega^2} = Q \frac{\pi G \Sigma R^3}{GM_*}$$

Less Massive



More Massive



Dependence on disc mass

Number of spiral arms depends on disc mass.

Why?

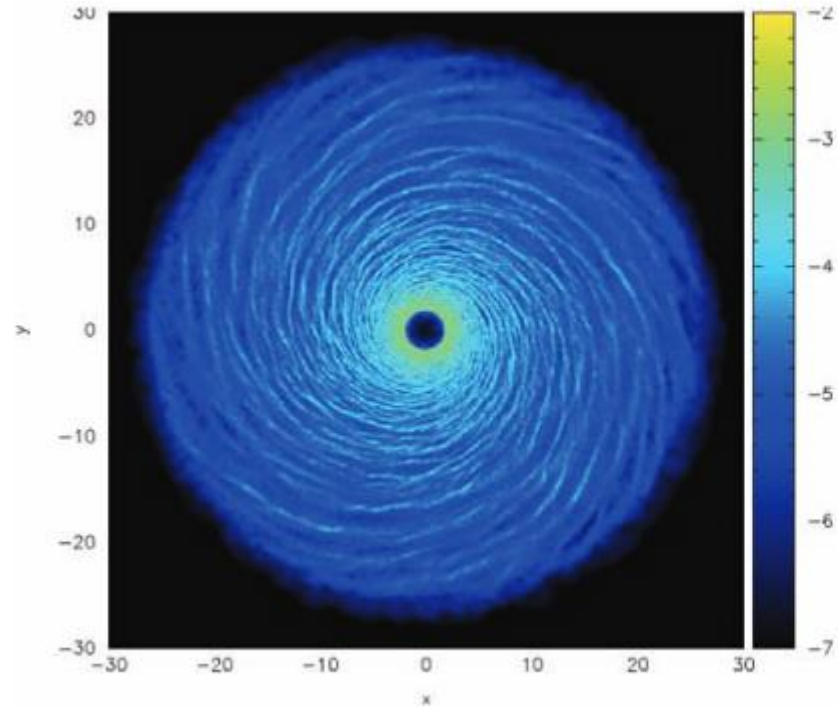
$$c_s = Q \frac{\pi G \Sigma}{\Omega}$$

$$H = Q \frac{\pi G \Sigma}{\Omega^2} = Q \frac{\pi G \Sigma R^3}{G M_*}$$

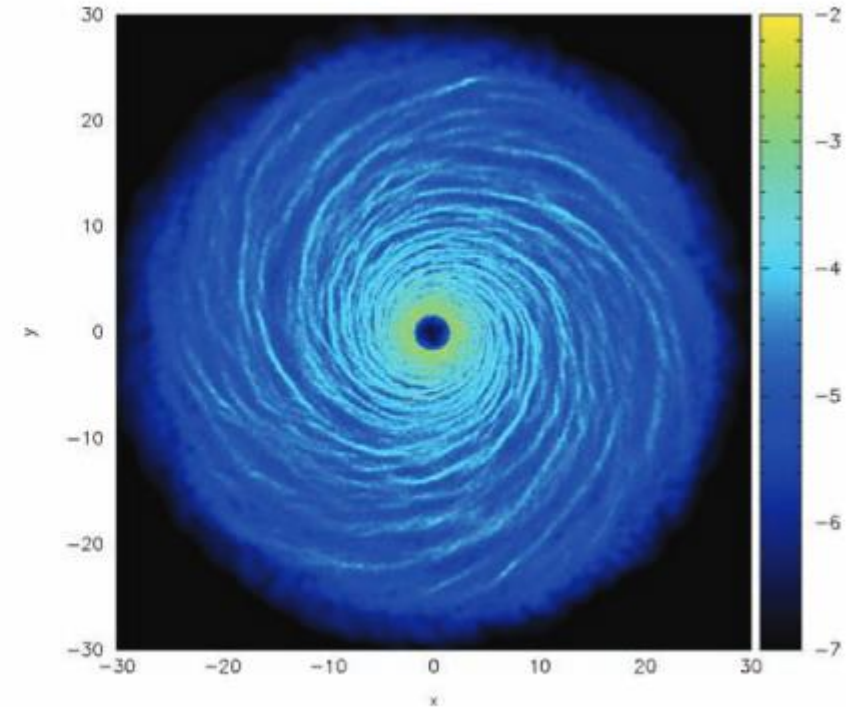
Or

$$\frac{H}{R} = Q \frac{\pi R^2 \Sigma}{M_*} \sim Q \frac{M_d}{M_*}$$

Less Massive



More Massive



Most unstable wavelength scales with H.

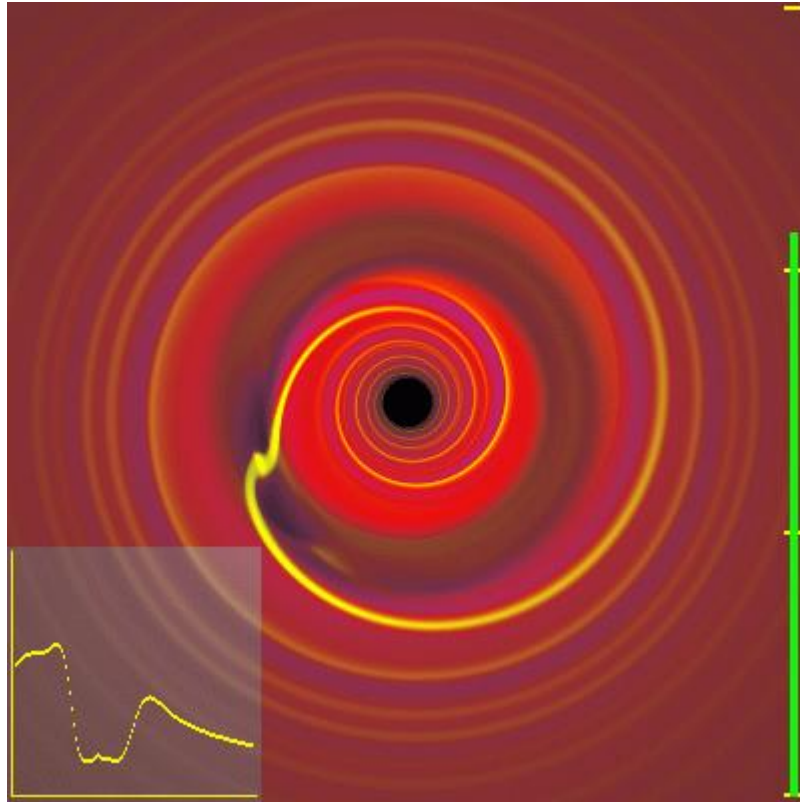
→ Number of spirals $\sim \frac{H}{R} \sim \frac{M_d}{M_*}$

Cossins+ (2009)

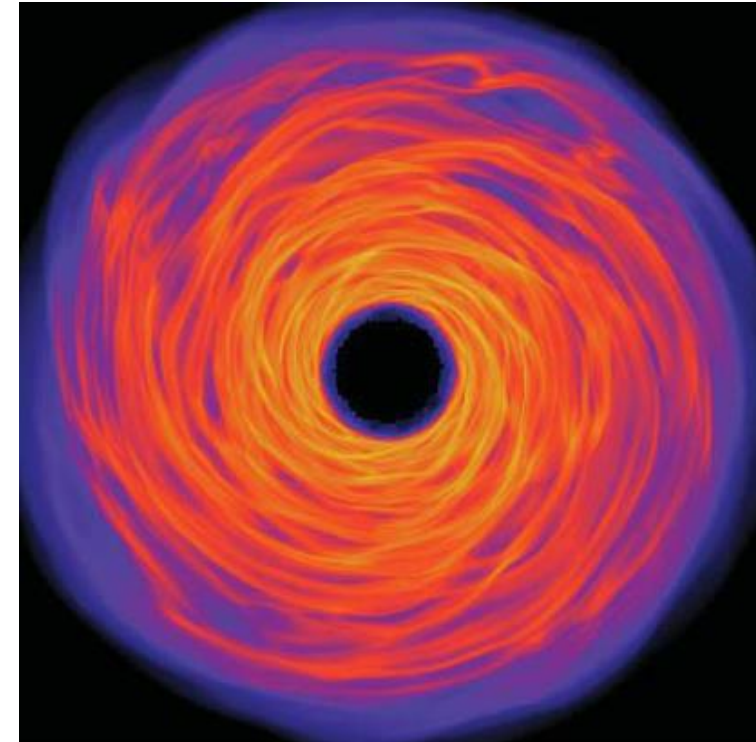
Project:

Dust in quasi-steady GI discs

Planet vs GI spirals



- Spiral rotates with planet
- Long lived steady spiral

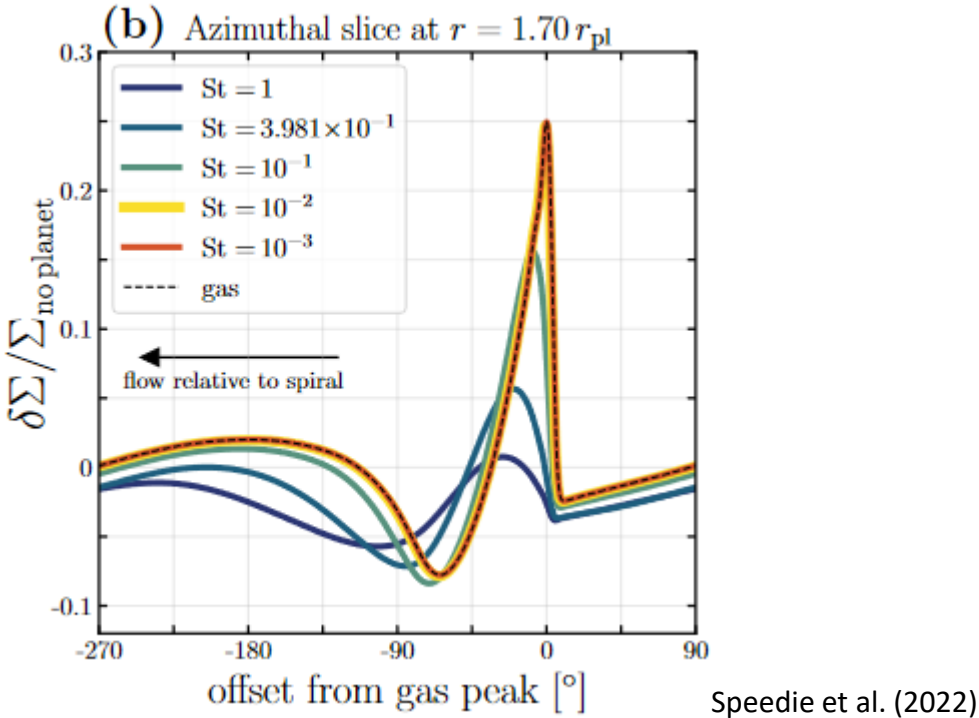


- Spiral rotates with the gas
- Individual spirals are short lived

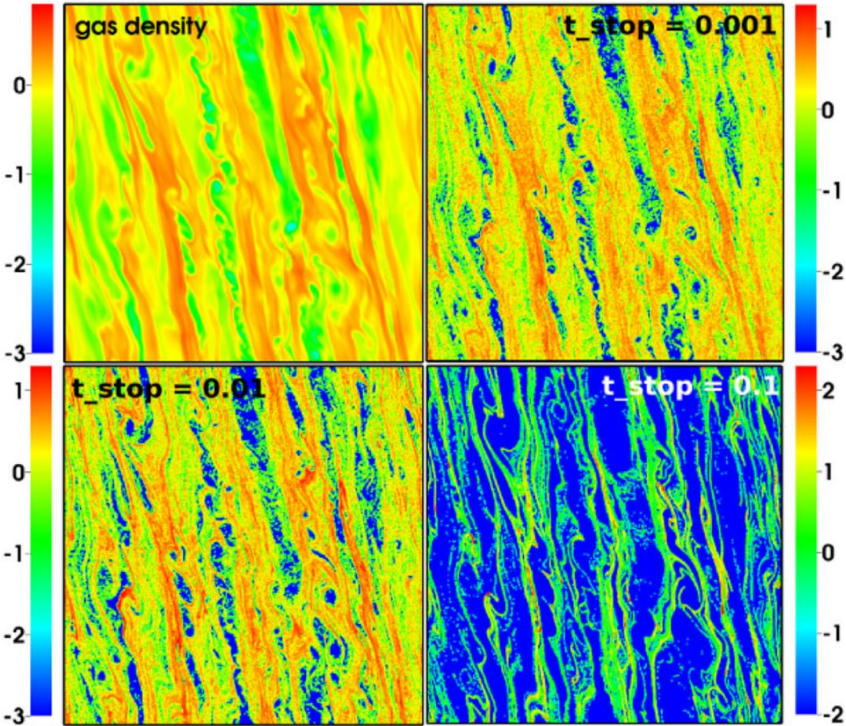
Dusty spirals

Differences in structure

Problem:
Can we tell planet and GI induced spirals apart observationally by their grain-size dependence?



- Strongest for small grains



- Strongest for large grains

Shi et al. (2016)

Dusty Spirals

GI

Approach:

- Use FARGO3D to simulate dust dynamics in spiral discs
- Explore how the dust-to-gas ratio varies for different sizes
- Compute simulated observations
- Compare with planet case

Key questions:

- What disc parameters should you choose?
- What dust parameters?
- What else might matter?